Study the Effect of Traffic Heterogeneity in a Coordinated Corridor using Simulation

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Abstract -- Urban roads are experiencing a significant period of congestion and delay due to traffic signals. Traffic signal timing optimization and coordination is easy and very cost-effective way to improve the flow of traffic along the corridor. By altering and retiming existing traffic signals to the traffic flow variations, the efficiency of each intersection will improve. For the study, the Chennai Airport to Kathipara intersections was taken. The stretch has seven signalized intersections. The morning peak flow was during 8:00am and 9:00am. Signal timings were optimized using Macro Simulation software. The vehicular flow in PCU values and link attributes are given as input and the signal timings were optimized and coordinated with offset timings. The traffic flow in the network was simulated with the aid of micro simulation software to understand the vehicle to vehicle interaction and flow characteristics at micro level. The study findings are reported in this paper.

Index Terms -- Coordination, Offset timings, Optimization, Signal timings.

I. INTRODUCTION

Signal coordination is occurring when a two or more signals are working together as a group, so that cars moving through the group will make the least number of stops as possible. Traffic is increasing at a rapid pace, proportional to the increasing population in all the cities in all the countries. As the traffic increases it causes traffic congestion. So different approaches can be used to minimize the traffic problem, such as, improving public transport, Expanding the communication mechanism, Proper handling of signal time, Consider the above the first two approaches require many resources as money, labor, area etc. They seem very difficult to achieve in many places due to lack of resources. Control of traffic light signal timing and signal coordination is least expansive and most effective means of reducing vehicular congestion in urban arterial. In urban arterial where traffic signals are nearby, the co-ordination of adjacent signals are very important and gives a greater benefit to the road users by increasing the utilization per unit time in the peak hours. Signal co-ordination plans are designed to reduce overall vehicle delay, reduce travel time, reduce fuel consumptions, reduce vehicle emissions, reduce road congestion, and also reduce neighborhood infiltrations. The following key elements are in signal coordination. Cycle Time, Green Time, Offset, and Phase. In signal coordination process Micro simulation and Macro simulation software's are used. Micro simulation is a design and signal coordination process.

II. BACKGROUND OF THE STUDY

Advanced Traffic analysis center, Signal coordination Strategies Final Report clearly defined about the different coordination method and their approaches and different coordinated software's. Number of simulations software s is there. In which the best software is to determine for Micro and Macro simulation and Optimization [1]. Influence of Signal Coordination on travel time and delay this paper deals with, by using the signal coordination process the performance indexes like travel time and delay is minimized to certain percentage [5]. Arterial Signal Coordination with uneven cycling this paper deals with the various cycle length. The two different cycle lengths are used in a field condition means it is necessary to optimize the cycle length and signal time using macro simulation software for coordination process. By this optimization of cycle length having minimum delay [7]. Simulation of Traffic Flow in CBD Road Network of Madurai city, deals with heterogeneous traffic flow of traffic for a CBD road network, and after coordinating the corridor using simulation the performance indexes are minimized as compare to existing field conditions. For coordination process micro simulation software is used [10]. Traffic Signal Coordination as a measure for an Urban Arterials in Chennai city, this paper explained about, by the signal coordination process urban arterial is involving the smooth flow of traffic, and to minimize the delay, queue, travel time, fuel etc. [14]. In a micro simulation software is also used to understand the vehicle to vehicle interaction and also it works on the models of simulating the Driver Behavior which includes the Car Following model, Lane change model, and lateral behavioral with in a lane. From the past studies they were used either micro or macro simulation software. But for my study the Micro and Macro simulation both were used, so we are obtained an effective result of ensure minimum delay, stops, queue etc.

III. METHODOLOGY

For any case, it is necessary to know about the need for study to find out the major problems. After establishing the need for the study, the objectives were formulated for carrying out the study. Various literatures were collected and reviewed and have been discussed briefly in the previous chapter. After reviewing the literatures, the study area was selected in Chennai city. Chennai Airport to Kathipara is selected as a study section. Data required for the analysis is broadly classified as Primary Data and Secondary Data. Primary data has been collected through traffic volume count survey by manually, road geometry details and speed of vehicles. And secondary data is number of phases and green time of each phase. After completing the Data collection

process building of a micro simulation model is an important factor in this one the vehicle input, vehicle routing, signal design procedures is carried out. Once the signal plan is obtained from Macro simulation, the simulation of the situation is done in Micro simulation. For this, two are more scenarios can be taken and based on the indices of delay, speed, queue length and cost, best resulting scenario is proposed and recommended as a result of the work.

IV. MODEL DEVELOPMENT

A. Optimization of Traffic Signal Time in Micro Simulation

Traffic signal optimization is the process by which the timing parameters are changed relative to the length of the green light for each traffic movement and the timed relationship between signalized intersections. Optimizing traffic signal timing reduces both deceleration and the acceleration of vehicles, leading to less fuel being burned and less carbon dioxide emissions etc. the following steps are to be followed in optimization of signal timing process.

Step 1: Optimal Cycle Time Estimation of Individual Junctions

The signalized junctions are initially designed in TRANSYT to study how the signal actually works and how it results with delay. The link resembles the flow of traffic and the Node resembles the junction. The other inputs are lane configuration with saturation flow, distance between intersections, cycle length, phase sequence and minimum green. After designing the junctions, the Cycle Time Optimizer (CYOP) is processed for the signalized junctions. This ensures that the cycle time of the junctions gets optimized. The optimization is done by comparing the performance index against cycle time. From this, the optimizer recommends a cycle time for the best resulting performance index.

Junction Name	Phase 1	Phase 2	Phase 3	Total Cycle (Sec)			
International Terminal	52	48	-	100			
Domestic Terminal	57	43	-	100			
Meenambakkam Metro	50	30	-	80			
S2 Airport Police Station	60	35	25	120			
Nanganallur Road	62	35	23	120			
Near SaravanaBhava <mark>n</mark>	42	33	1	75			
Near Alandur Metro	48	32	-	80			

 Table 1 Phase Time of the Network after Optimizing

Step 2: Identification of Critical Junction and Cycle Time of other Junctions

Using Cycle time optimizer (CYOP) the cycle time of every junction is optimized. The cycle time is chosen between 0.75 times to 1.25 times of the critical cycle time so as to ensure that it results for minimum delay. Among the seven junctions, the critical junction is determined. Based on that the other junction's cycle is either made half or multiple of the cycle times for coordinating signals.

Table 2 Common Cycle Time of the Network							
Junction Na <mark>me</mark>	Phase 1	Phase 2	Phase 3	Total Cycle (Sec)			
International Terminal	38	22	-	60			
Domestic Terminal	35	25		60			
Meenambakkam Metro	40	20		60			
S2 Airport Police Station	58	37	25	120			
Nanganallur Road	55	42	23	120			
SaravanaBhavan	34	26	-	60			
Alandur Metro	40	20	-	60			

 Table 2
 Common Cycle Time of the Network

Step 3: Devising Coordination Plan

Optimization can be done based on Offsets, Offsets and Green Splits, Extended Offsets and Green Splits. Based on the requirements, the Optimization is given to the model. Once it is optimized, the offsets for each junction can be established to ensure coordination between the junctions.

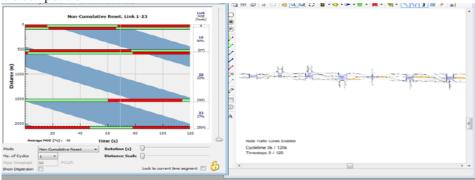
Table 5 V	Juset and Oreen	I mile for be	cych gun	cuons		
Junction Name	Cycle Time	Bhogo Green P		Period	Croop Splits	
	(Sec)	Phase	Start	End	Green Splits	
International terminal	60	1	12	38	26	
International terminal	00	2	38	54	16	
Domostic terminal	60	1	19	36	17	
Domestic terminal	00	2	36	57	21	
Meenambakkam Metro	60	1	11	39	28	
		2	39	54	15	
S2Airport Police Station	120	1	19	59	40	
		2	59	89	30	
		3	89	111	22	
		1	15	54	39	
Nanganallur Road	120	2	54	87	33	
		3	87	114	27	

Table 3 Offset and Green Time for Seven Junctions

SaravanaBhavan	60	1	21	42	21
		2	42	54	12
Alam dan Matus	(0	1	12	42	30
Alandur Metro	60	2	42	54	12

Time Space Diagram for Various Scenarios

Time-space diagrams are created by plotting the position of each vehicle, given as a distance from a reference point, against time. Time space diagrams are plotted for various scenarios. Fig 1 represents the vehicle move from one junction to another junction it is continuously stopped. So delay is occurring in existing scenario for existing vehicle composition. Fig 2 represents the vehicle move from one junction to another junction it is continuously stopping so it ensures minimum delay in coordinated scenario for existing vehicle composition. Fig 3 represents vehicle move from adjacent junctions slightly stopped and creates delay in existing scenario with changing vehicle composition. And finally fig 4 represents the vehicle moves from adjacent junctions continuously green without any stopping so its ensure minimum delay in coordinated scenario with changing vehicle composition.





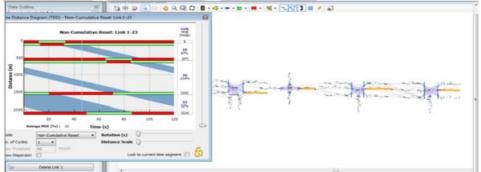
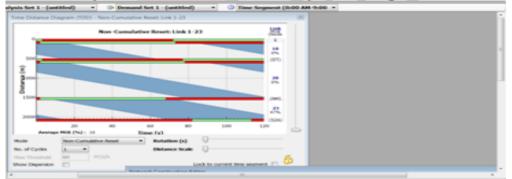


Fig 2. Coordinated Scenario for Existing Vehicle Composition





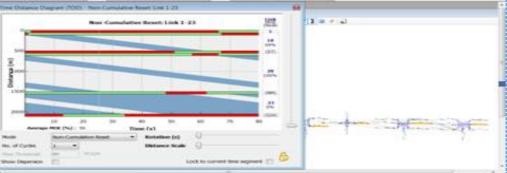


Fig 4. Coordinated Scenario for Changing Vehicle Composition

B. Micro Simulation

Step 1: Traffic Input

Vehicle inputs must be given in volume. Vehicle composition comprises two wheelers, Two Wheelers, Cars, Autos, Buses and Trucks. Two wheelers of 58%, Autos of 4% and Cars of 35% are the dominating vehicle compositions. Other parameters such as vehicle Types, classes, design speed, acceleration and deceleration rates etc are given. They are given to represent the real-time existence of traffic flow, properties and speed.

Step 2: Vehicle Routing

It is the path which the vehicle adopts to travel in real-time. For each destination from a single origin, routing must be provided. It is the most important process which also includes the split of vehicle composition with relative flow.

Step 3: Signal Head and Simulation

Based on the existing phases and cycle time, the signals are designed and the signal heads are placed in the network at the appropriate places. From the signal controller program, signals can be created for junctions. For the signalized intersections, priority is given to the major traffic. This will help the junctions to perform well in the network. The network is simulated and calibration is done so as to ensure that the network model resembles the exact ground scenario.

V. CALIBRATION

Validation is essential for a model to validate it with the exact situation which prevails in the reality. Calibration of a micro simulation model for mixed traffic requires special procedures to address the unique characteristics of such traffic. Accordingly, a representation of vehicles, geometry and traffic, followed by identification of calibration parameters by multi parameter sensitivity analysis, setting their ranges heuristically and determining the parameter values by an optimization model. Validation of Micro simulation model can be done by calibrating the routing as per the In-flow and Out-flow at each junction. The major factor is the Driving behavior. The traffic representation addresses several distinct features of mixed traffic.

4.1. Driving Behavior

In driving behavior parameter as we can define the driving behavior properties of a link. Under this, there are four parameters namely following behavior, Lane change behavior, Lateral behavior and Behavior at Signal controllers. Each of the parameters is taken individually and simulated for the changes made and validated.

4.2. Following Behavior

In a Following Behavior, look ahead distance, look back distance, car following model and standstill distance play a major role. The supporting factors are additive and multiplicative part of safety distance, smooth close-up behavior.

4.3. Lane Change Behavior

In a Lane Change Behavior is the general behavior, maximum deceleration of own and trailing vehicle, cooperative lane change and lateral correction of rear end positions play a major role. The supporting factors are accepted deceleration, minimum headway, advanced merging etc.

4.4. Lateral Behavior

In a Lateral Behavior the desired position of free flow, lateral distance exceptions play a major role. In this one it is necessary to provide appropriate lateral distance for each vehicle category according to its exceptions. The supporting factors are considering next turn movement, overtake on same lane etc.

4.5. Signal Control Behavior

In a Signal control behavior, the parameters are checked for reaction to amber and behavior at red/amber. These two govern the behavior of vehicles at a signal.

VI. SCENARIO ANALYSIS

Scenarios are formulated and comparisons can be made between them to propose the best resulting scenario based on vehicle distance travelled, travel time and delays. In the study, four scenarios are proposed.

Scenario 1: Existing scenario with existing vehicle composition.

The first scenario is to model the existing road with uncoordinated signals. As a result of calibration of the existing road network was found and Network performance index are taken for the comparison.

Scenario 2: Coordinated scenario with existing vehicle composition.

The second scenario is to coordinate the existing signals in the road network. As a result, the vehicle entering into the network was found and Network performance index measures are compared.

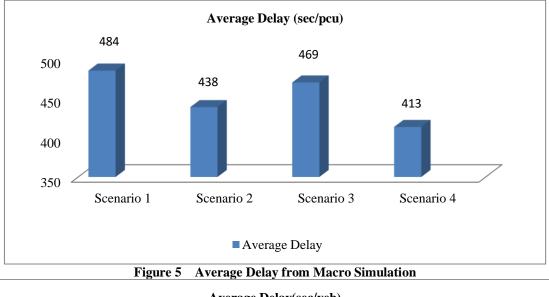
Scenario 3: Existing scenario with changing vehicle composition.

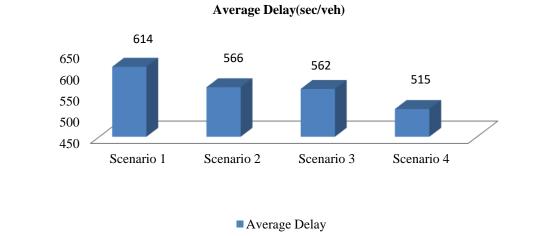
The third scenario is the existing UN coordinated signals with changing the vehicle composition. Te result of this scenario is by changing the vehicle composition and their impacts on performance index are compared.

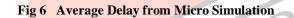
Scenario 4: Coordinated scenario with changing vehicle composition.

The Fourth scenario is the coordinated signals with changing the vehicle composition. The result of this scenario is by changing the vehicle composition and their impacts on performance indexes are compared.

From the work, the comparison of the scenarios can be studied from both Micro simulation and Macro simulation results.







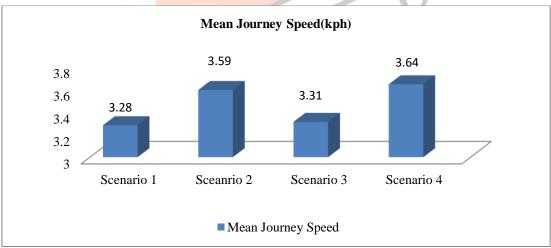


Fig 7 mean Journey Speed from Macro Simulation

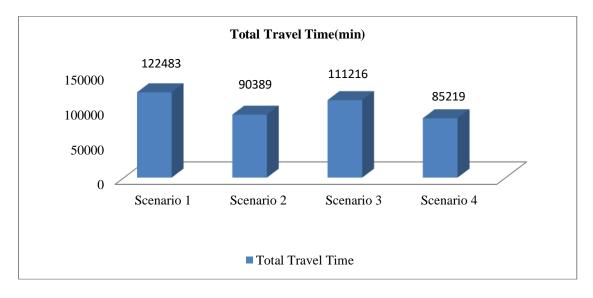


Fig 8 Total Travel Time from Micro Simulation

VII CONCLUSION

The result of the study is Delay was reduced by 10% for the coordinated scenario and 15% reduction for changing the vehicle composition with coordinated scenario in Macro simulation. In the coordinated scenario delay got reduced by 8% and changing the vehicle composition with coordinated scenario got reduced by 16% in Micro simulation. Journey speeds were also obtained from Macro simulation. It is found that the journey speed has increased for coordinated and changing the vehicle composition with coordinated scenario with existing conditions. Journey speed has been improved by 9% for the coordinated scenario and 10% improvement for changing the vehicle composition with coordinated scenario. When compared with the existing scenario, the total travel time for coordinated and changing the vehicle composition with coordinated scenario is reduced. And the number of persons travelled is increased during changing the vehicle composition with coordinated scenario.

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